

CSI 5109

**Specification Methods  
for Distributed Systems**

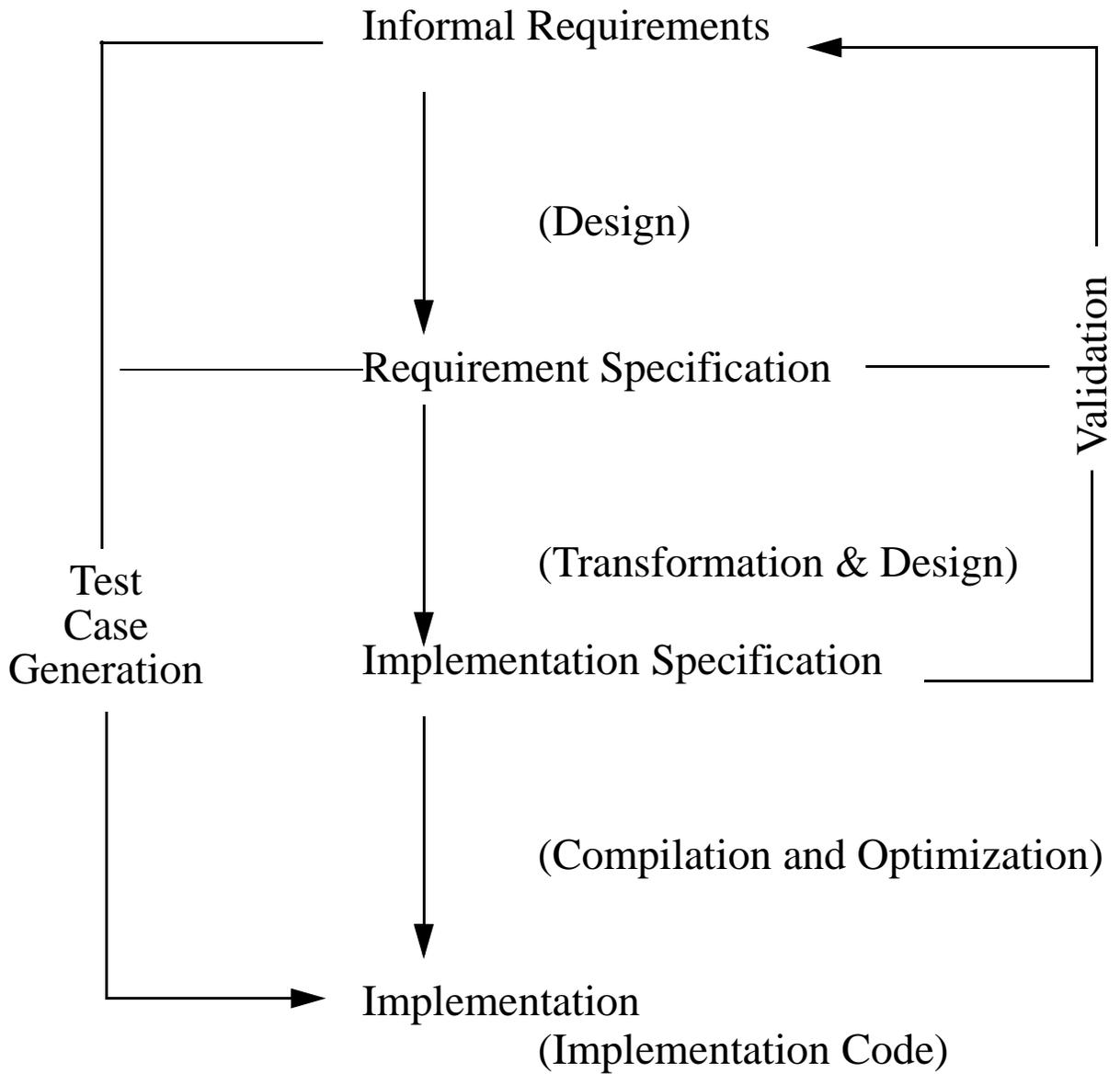
*Course notes by*

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# A (Simplistic) View of the Software Development Process



The earlier a potential problem is detected in the software lifecycle, the smaller its cost is.

**By specifying and validating a system at the design stage, many design ambiguities and errors can be identified before implementation starts**

# **Formal Description Techniques (FDTs) or Formal Specification Languages**

Languages for the precise specification of the functionalities of software.

They must have a math basis (*formal*).

They can be used in all phases of the process: requirements, implementation, testing...

**In what do they differ from programming languages?**

At the specification level, there is no need for execution efficiency, so we can use more abstract concepts

**However:**

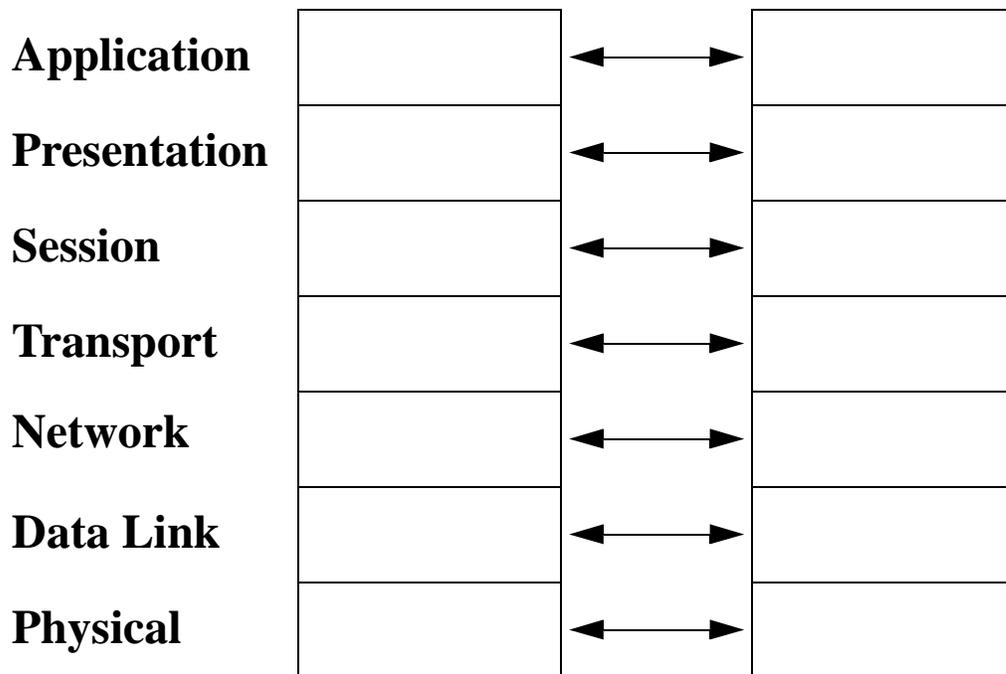
Is today's specification language tomorrow's programming language?

# HISTORY

In 1978, ISO and CCITT (now ITU) set out to define a new family of standards for data communications protocols

## The Open System Interconnection

OSI



## The Seven-Layer “Reference Model”

OSI was never fully implemented,  
however it generated many useful ideas

## FDT for OSI

One of the requirements of OSI standardization was to have one (or more!) techniques for the **formally precise** specification of the standards.

(A standard can only be effective if it is precisely specified, in an implementation-independent fashion)

*Note:* in this course, we shall be concerned only with telecom-related FDTs.

## FDTs

USE	FEATURE
Directives to implementors, Communication between implementors. Standardization	Well-understood, unambiguous, precise, simple All the "natural" concepts, abstract, non-procedural
Verification, formal testing	Logically sound -> Proofs Executable, Support of test techniques
Design tools	Modularity, abstraction levels

## **A Great Number of Open Problems:**

### **Expressive Languages**

Suitable both for automatic processing and human use to express requirements at various levels of abstraction.

### **Design and Transformation Techniques**

To move between levels of abstraction

### **Validation Techniques**

To prove consistency between levels of abstraction

### **Derivation of Test Cases**

To test consistency

**Etc. Etc.**

## **Theoretical Developments**

Happily, just as these needs were being recognized, some theories were being developed, which had potential for meeting them.

- Automata theory and its extensions
- Language theory and its extensions
- Theory of Communicating Sequential Processes (Hoare's CSP)
- Calculus of Communicating Systems (Milner's CCS)
- Temporal Logic

etc.

## Some standard FDTs

<b>SDL</b> (Specification and Description Language)	Extended FSM model	An ITU (CCITT) standard
<b>ESTELLE</b>	Extended FSM model - Pascal-base	An ISO standard
<b>LOTOS</b>	CCS, CSP, Act One	An ISO standard
<b>ASN.1</b>	A notation for specifying data formats	An ISO/ITU standard
<b>TTCN</b> (Tree and Tabular Combined Notat.)	A notation for specifying test cases	An ISO/ITU standard

## A Personal View of FDT progression

In the early seventies, the main model for telecom specification was the *communicating finite-state machine* (FSM) model. This was the initial SDL model.

This model was not powerful enough to express protocols (little data), hence the Extended FSM model: today's SDL, Estelle.

Process algebras (CCS, CSP) came about in the eighties. They had more sophisticated semantics, expressed in LOTOS.

E-LOTOS (Extended LOTOS), defined in the nineties, adds extra expressive power but the basic model is the same.

We can expect more sophisticated models from newer theoretical developments (e.g. category theory, linear logic). However efforts in this direction are still immature.

# LANGUAGE OF TEMPORAL ORDERING SPECIFICATIONS

Meaning that the language defines the temporal ordering of events in time (but not their precise time of occurrence).

Consists of *two main parts*:

*Behavior part*, to specify ordering of events. Main influences:

- CCS: Milner's Calculus of Communicating Systems
- CSP: Hoare's Communicating Sequential Processes

*Data part*, to specify the data abstractions:

- ACT ONE Abstract Data Type formalism

# Ohm's Law

$$V / A = R$$

*or*

$$V = A \times R$$

*or*

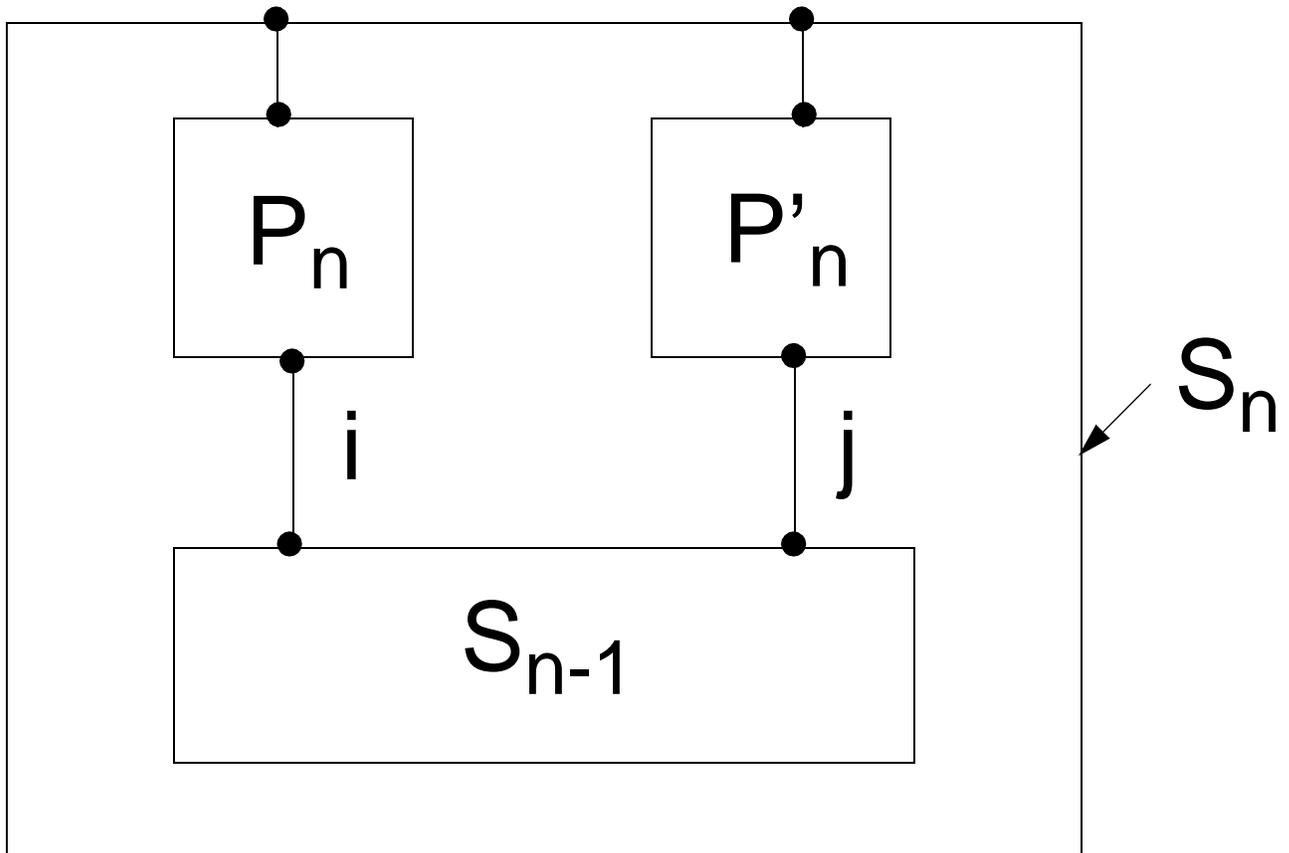
$$A = V / R$$

**Engineering is made possible largely  
by the existence of such laws,  
and by our ability to manipulate them  
symbolically, yielding other useful laws.  
*This is algebra***

**Formal methods**  
in software seek to use  
mathematics in software  
in the same way as  
mathematics have been  
used in engineering: to  
provide symbolic models  
for the behaviour and  
properties of an artifact.

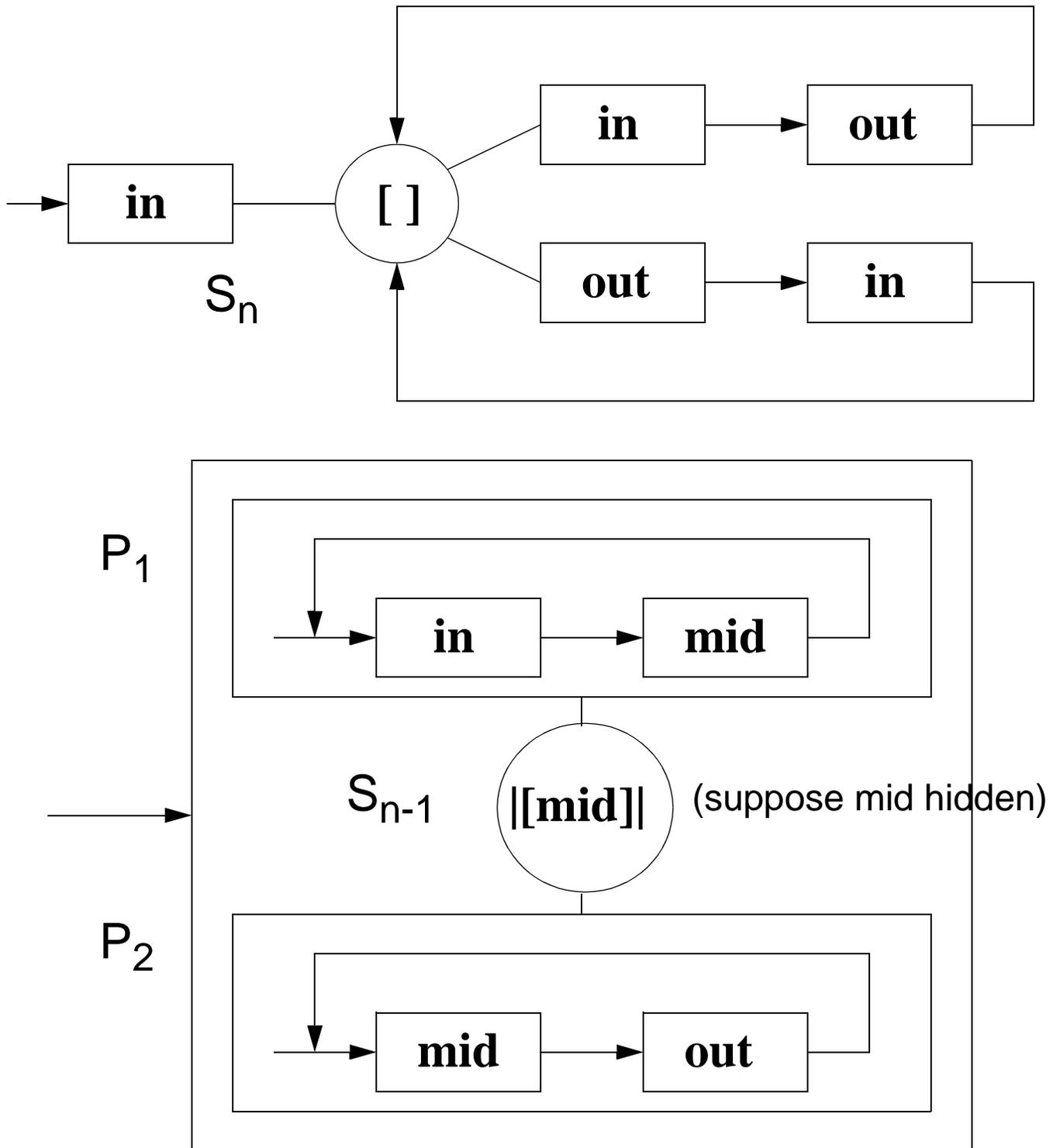
What we need is a *mathematics of distributed software* by which programs and specifications can be manipulated symbolically with the same ease as we can manipulate algebraic expressions.

E.g., in a layered protocol model (OSI-like)



it would be useful to be able to conclude formally that  $S_n = (P_n \parallel P'_n) | [i,j] | S_{n-1}$   
 (let  $S_n$  be a service provider of layer  $S$ , which is realized by two protocols  $P_n$  and  $P'_n$  over a service provider of layer  $S_{n-1}$ . These communicate with  $S$  by two service access points  $i$  and  $j$ )

An example of very simple equivalence provable in LOTOS:



Two different specifications for a buffer capable of storing a maximum of two signals.

A real *mathematics of distributed software* does not yet exist. However, its laws are slowly becoming understood (how many centuries after the first bridge did the engineering and mathematical laws underlying bridge construction become clear?)

The need of *efficient computation* on a Von Neumann machine leads to sequential thought which is not conducive to mathematical thinking. Many small functions are involved, the order of execution is important, functions have side effects.

The logical clumsiness of low-level software can be hidden by increasingly abstract languages, that have increasingly nicer mathematical properties. plus rules of transformations between such languages.

LOTOS is a specification language for distributed systems where many “nice” mathematical properties (a *process algebra*) hold:

$$\begin{aligned}\mathbf{B}_1 \parallel \mathbf{B}_2 &= \mathbf{B}_2 \parallel \mathbf{B}_1 \\ \mathbf{B}_1 [] \mathbf{B}_2 &= \mathbf{B}_2 [] \mathbf{B}_1\end{aligned}$$

$$\mathbf{B}_1 \parallel (\mathbf{B}_2 \parallel \mathbf{B}_3) = (\mathbf{B}_1 \parallel \mathbf{B}_2) \parallel \mathbf{B}_3$$

$$\mathbf{B}_1 [] (\mathbf{B}_2 [] \mathbf{B}_3) = (\mathbf{B}_1 [] \mathbf{B}_2) [] \mathbf{B}_3$$

$$\mathbf{B} \parallel \text{stop} = \text{stop}$$

$$\mathbf{B} [] \text{stop} = \mathbf{B}$$

etc., etc.

It is possible to manipulate LOTOS formulae according to these algebraic identities, yielding conclusions about equivalence of formulae, etc..

This course will concentrate on  
LOTOS.

However it intends to be a general introduction on

*algebraic techniques*

for specifying, validating and testing distributed systems and their protocols

# LOTOS PHILOSOPHY

## *Executability:*

- **Fast Prototyping**
  - **early detection of design errors**
- **Lifecycle Support**

## *Mathematical Basis:*

- **Algebraic manipulation of Specifications**
- **Support of various types of Validation**

## Some basic LOTOS ideas (will be clearer later):

Formal, mathematical definition:

Syntax (usual BNF)

Static Semantics (attributed grammar)

Dynamic Operational Semantics  
(inference rules)

Data algebra for defining data properties

Process algebra for defining behavior properties

Process encapsulation [object *based*]  
processes communicating by messages

Process parameterization

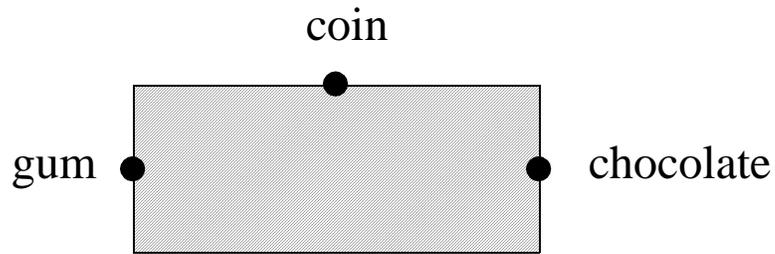
Interleaving parallelism:

A in *parallel* with B means that actions of A and B are allowed to *interleave* arbitrarily

# LOTOS AND SOFTWARE LIFECYCLE

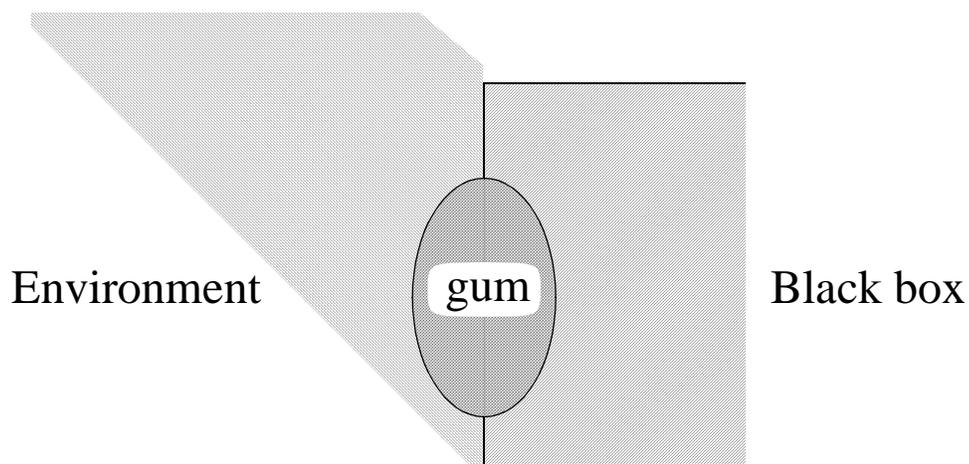
	<b>FEATURES</b>	<b>TOOLS</b>
<b>DESIGN</b>	Expressiveness Modularity	Graphic LOTOS-Graphic editors Syntax, static semantics checkers
<b>DESIGN VERIFICATION</b>	Precisely defined semantics Verification rules Executability of Specifications	Computer-assisted verification tools for static, dynamic verification
<b>IMPLEMENTATION</b>	Executable	Computer-assisted translation "abstract_LOTOS" -> implementation -> executable code
<b>VERIFICATION AND TESTING OF IMPLEMENTATION</b>	Precise testing theory Test trees can be obtained from specifications Verification rules	Generation of "useful" execution trees and test sequences. Computer-assisted verification tools
<b>MAINTENANCE</b>	Documentation Modularity Implementation independence	Verification of "persistence" of properties

## A “Black Box” and its Interaction Points (or “synchronization points”)



Execution of an “action” at a “gate” requires participation of both environment and box

So the execution of an action is called “synchronization”



The synchronization point is a shared mechanism of box and environment

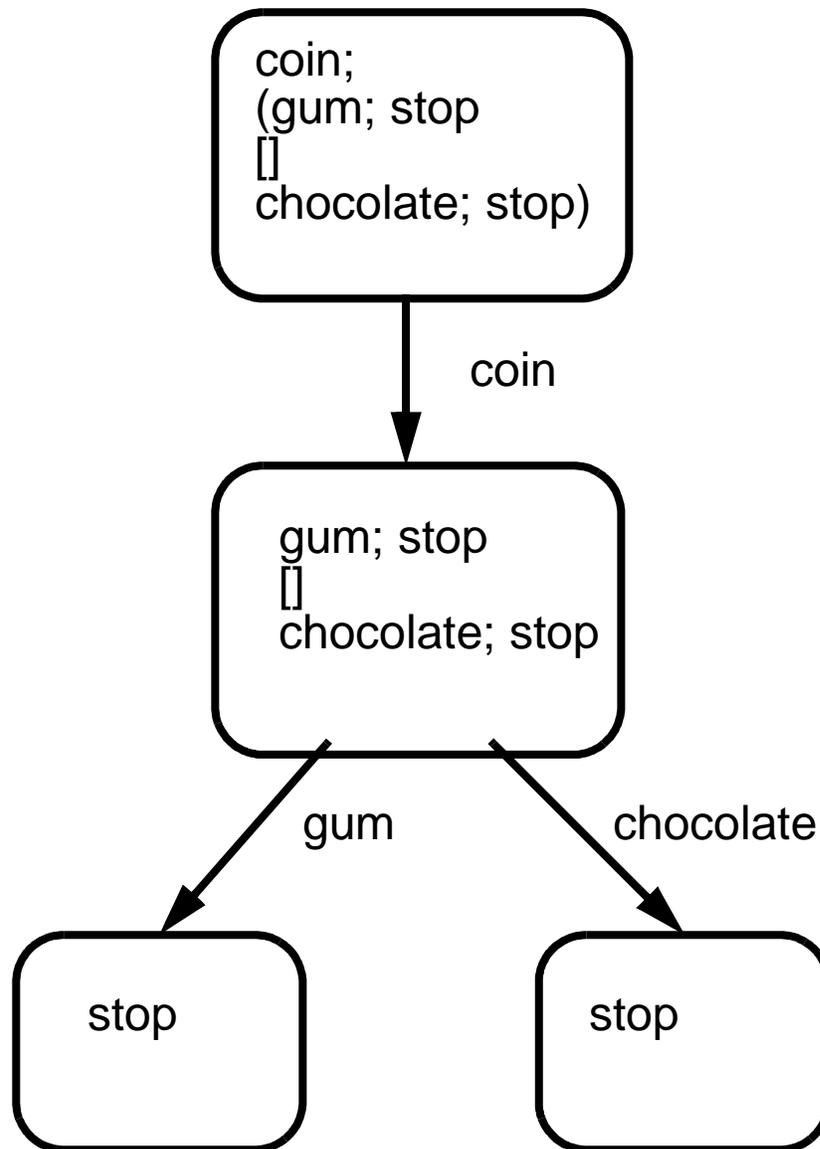
Environment can be other processes or the external world

Some synonyms: interaction, synchronization, rendezvous

**A LOTOS *behavior expression*:**

```
coin;  
  (gum; stop  
  []  
  chocolate; stop)
```

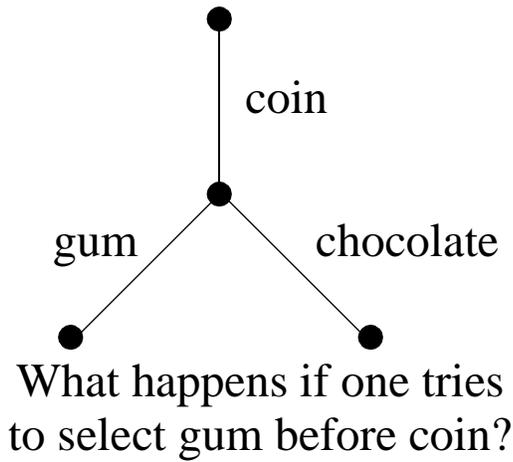
**describes a black box that can take a *coin* and then give *gum* or *chocolate*.**



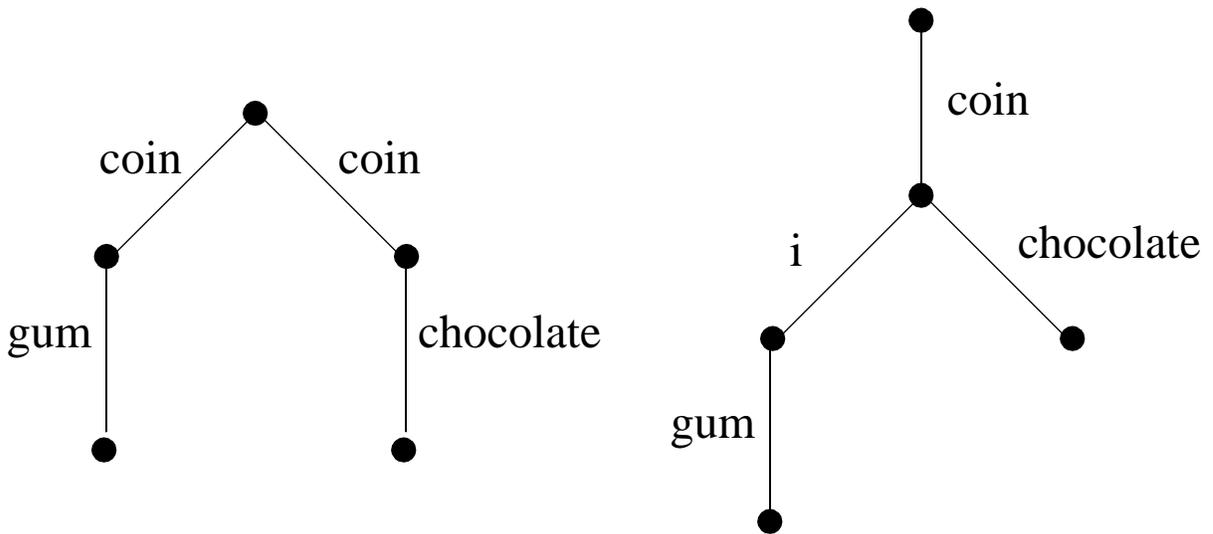
A LOTOS behavior tree: states are behavior expressions, transitions are actions. (also called: synchronization tree, Labeled Transition System...)

# Behavior Trees to Represent Finite Behaviors

(Also called *synchronization trees*)

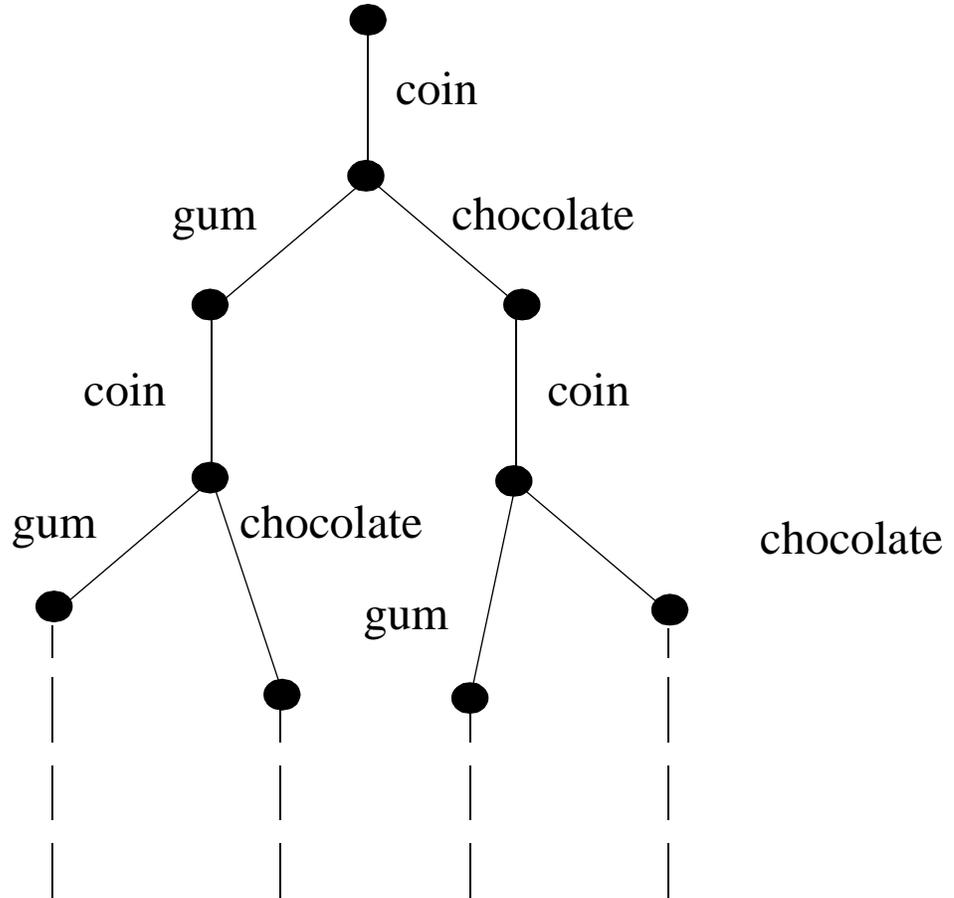


What happens if one tries to put a second coin in?

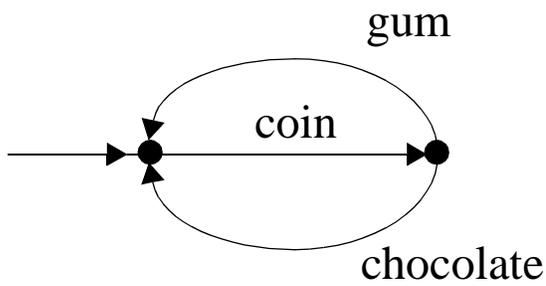


Any difference in observable behavior?

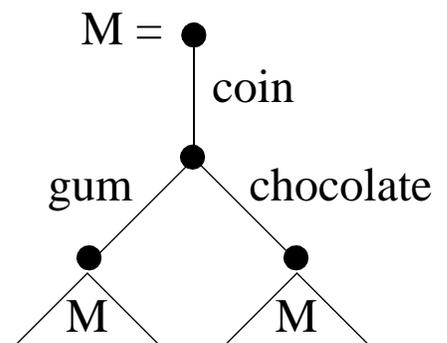
Trying to represent infinite behavior  
by behavior trees



*A labeled transition system*



or also



A Labelled Transition System (LTS) is a directed, connected graph where each edge (denoting a state transition) is labelled by the name of an action,

- external or
- internal (= **i**).

LTSs are used to describe the behavior of processes.

Traversal of an edge labelled by an external action means that the environment and the process have agreed to **execute** the action.

We also say that the environment and the process **synchronize** on the action. However **i** can be executed independently by a process.

LTSs are also called **behavior** or **synchronization** graphs. When *unfolded* as trees, they are called *behavior* or *synchronization trees*.

Note:

Process instantiations, guards, behavior expressions such as **stop** or **exit** etc. cannot label edges.

## Behavior Expressions in LOTOS

A behavior expression represents at the same time

- the state of a process (i.e. a black box, a system)
- its labelled transition system

In other words, the state of a process is the set of potential behaviors of the process.

There are two predefined behavior expressions:

**stop** or deadlock

**exit** or successful termination

There is one predefined action:

**i** the internal action

More complex behavior expressions can be obtained by combining actions and behavior expressions by using operators, process definitions, process instantiations, etc. as we shall see ...

A LOTOS behavior expression specifies the "externally observable" behavior of processes which communicate with the environment by means of "actions" at "gates":

E.g.

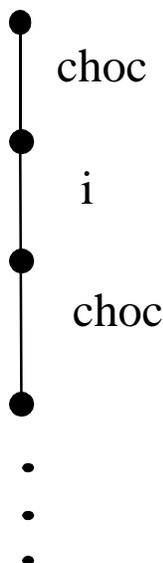
```

process P [choc] :=
    choc; hide rumble in rumble; P[choc] (*recursion!*)
endproc
  
```

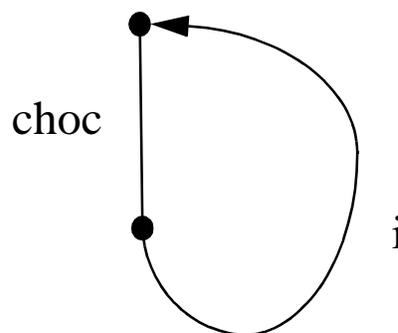
is a process that keeps offering to interact with the environment at gate *choc*. It hides action *rumble*. Recursion is used to represent a repeating process.

if the environment collaborates,  
 P will keep offering choc  
 if at some point the environment does not collaborate,  
 P will **stop** (or "deadlock").

Behavior tree for P:



LTS for P:



## Basic LOTOS Operators

**;** Action prefix (Sequencing actions  
and behavior)

**[ ]** Choice

**||**

**| [ ... ] |** Parallel composition

**|||**

**hide** Hide some actions

**>>** Enabling (Sequencing two behaviors)

**[ >** Disabling (A behavior can interrupt  
another behavior)

**P ( ... ) [ ... ]** Process Instantiation

## Concepts discussed in Class 1:

- Why formal techniques
- Some history
- Basic principles of LOTOS:
  - algebraic
  - concept of synchronization (symmetric)
  - environment
  - states and transitions
  - external and internal actions
  - behavior trees, LTS
  - behavior expressions as states
  - list of basic operators

*And whosoever of them ate the honey-sweet fruit of the lotos [...] wanted to abide there among the lotos-eaters, feeding on the lotos*

(Homer, Odyssey)

## Reference Materials to get started

### **Go to:**

<http://LOTOS.csi.UOttawa.ca/ftp/pub/Lotos/Intro/>

### **Download**

Logrippo, L., Faci, M., and Haj-Hussein, M. "An Introduction to LOTOS: Learning by Examples.

Bolognesi, T., and Brinksma, E. Introduction to the ISO Specification Language LOTOS

Turner Tutorial

### **At the Reserve in the Library, look for**

K.J. Turner (ED.) Using Formal Description Techniques (presents in detail LOTOS, Estelle, SDL with many examples)

Another introduction to LOTOS written by Ken Turner

### **Other materials on reserve (useful for projects and for those who want to know a lot...):**

Books by Milner (on CCS) and Hoare (on CSP), and by Ehrig and Mahr (on ACT-ONE)

Two books on European projects related to LOTOS

The ISO LOTOS standard